

EPN-Related Activities and Research at **ROB**: Status and Perspectives

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Solar-Terrestrial centre of

Excellence



Royal Observatory of

Belgium

Presentation of the ROB team (<http://www.gnss.be/who.php>)



Carine Bruyninx

??? □



Pascale Defraigne

PPP and Time Transfer



Quentin Baire

Quality Check & Antenna Calibration



Wim Aerts

Error Sources in Positioning and Timing Instrumentation, Engineering



Juliette Legrand

Reference Frame and Velocity Field



Nicolas Bergeot and Jean-Marie Chevalier

Modelling and Monitoring of the Ionosphere



Eric Pottiaux and Julie Berckmans

Modelling and Monitoring of the Troposphere



Dominique Mesmaker and Ann Moyaert

IT Technical support

Main EPN-related Activities and Research



EPN Central Bureau

(Bruyninx et al., "EPN CB Support to EPN Data Analysis and Future Strategy")



IAG WG "Integration of Dense Velocity Fields in the ITRF"

(Legrand et al., "Future EUREF contribution to the IAG WG 'Integration of Dense Velocity Fields in the ITRF' ")



EPN Data Centres & Broadcaster



(EPN-style) Data Analysis



PPP for Time Transfer



Antenna Calibrations



Monitoring of the Ionosphere



Monitoring of the Troposphere

EPN Data Centers

▪ ROB EPN Data Center:

- URL: <ftp://gnss.oma.be/gnss/data/rinex/>
- hourly and daily RINEX files of ROB's EPN stations (BRUS/BRUX, DOUR, DENT, WARE)

▪ EPN Historical Data Center:

- URL: <ftp://ftp.epncb.oma.be/pub/obs/>
- Daily EPN RINEX data (also "pre-EPN" data – but incomplete)
- Corrected RINEX headers according to site log – 3 month delay

```
[ 2 OBSERVATION DATA G (GPS) RINEX VERSION / TYPE
HEADER CHANGED BY EPN CB ON 2009-05-18 COMMENT
TO BE CONFORM WITH THE INFORMATION IN COMMENT
ftp://epncb.oma.be/pub/station/log/ankr_20080509.log COMMENT
COMMENT
RGRINEXO V2.4.2 VM IFAG-WETTZELL 04-JAN-96 10:12 PGM / RUN BY / DATE
BIT 2 OF LLI (+4) FLAGS DATA COLLECTED UNDER "AS" CONDITION COMMENT
0.000000000000 HARDWARE CALIBRATION (S) COMMENT
0.0000000084672 CLOCK OFFSET (S) COMMENT
ANKR MARKER NAME
20805M002 MARKER NUMBER
```

ROB EPN Broadcaster

- Caster URL : <http://www.euref-ip.be>
- User registration form:
<http://gnss.be/data.php#NTRIPaccess>

Welcome to the ROB EUREF RELAY GNSS Server

This server, available at www.euref-ip.be, is run by [Royal Observatory of Belgium, GNSS Team](#).

It aims at being a thematical server for all EUREF NTRIP streams.

The Belgian ROB stations BRUX0, BRUX1, DENT0, WARE0 are directly streaming to the caster.

The other EUREF stations are mirrored from 17 casters such as:

- the [caster](#) in CHE run by [SWISSTOPO](#) (for stations ZIM2_RTCM)
- the [caster](#) in CZE run by [GOP](#) (for stations GOPE0, GOPE1, TUBO0)
- the [caster](#) in ESP run by [IGN](#) (for stations ACOR0, ACOR1, ALAC0, ALBA0, ALME0, ARDU0, ARDU1, BCLN0, BORR0, CACE0, CANT0, CANT1, CEU10, COBA0, COBA1, FRAGO, GIRO0, HUEL0, IGNE0, IGNE1, IZAN0, IZAN1, JACA0, JORD0, LEON0, LEON1, LPAL0, LUGO0, MALA0, MALA1, MALLO, MALL1, MELI0, MER20, MER21, RIO10, SALA0, SALA1, SONS0, SONS1, TARI0, TERU0, TN010, TN020, TN030, VALE0, VIGO0, YEB10, YEB11, YEBE0, ZARA0, ZFRA0)
- the [caster](#) in FRA run by [IGN](#) (for stations AJAC1, BRST1, BSCN1, GRAS1, MARS1, SCOA1, TLSE1, VFCH1)
- the [caster](#) in GBR run by [OS](#) (for stations DARE_RTCM, INVR_RTCM, SHOE_RTCM)
- the [caster](#) in GER run by [BKG](#) (for stations AJAC0, AUT10, BELF0, BELLO, BOG10, BOR10, BOR11, BRST0, BSCN0, BUCU0, BUTE0, BZRG0, CAGZ0, CFRM0, CLIB0, CPAR0, CRAK0, CREU0, CTAB0, DARE0, DRES1, DUBR0, EBRE0, GANP0, GRAZ3, HERT0, HOE21, HOFN0, IENG0, IGEU0, INVR0, ISTA0, JOEN0, JOZZ0, KARL1, KIR00, KURE0, LAMA0, MOSE0, MAR60, MARS0, METS0, MOP20, NICO0, OBE40, ONSA0, ORID0, OSJE0, OSLS0, PAD00, PENC0, REYK0, ROVE0, SASS1, SKE00, SODA0, SOF10, SPT00, STAS0, SULP0, SUR4, TOIL0, TOR20, TOR10, TRD50, UNPG0, UNTR0, VAAS0, VALA0, VARS0, VFCH0, VIS00, WARN1, WROC0, WSR00, WTRZ0, ZIM20, ZOUFF0)
- the [caster](#) in GER run by [BKG](#) (for stations POTS0)
- the [caster](#) in GER run by [BKG](#) (for stations BRUX7)
- the [caster](#) in HUN run by [FOMI](#) (for stations PENC_RAW-RTCM3.0)
- the [caster](#) in ITA run by [UNIPD](#) (for stations Bolzano, Padova, Rovereto)
- the [caster](#) in ITA run by [E-GEOS](#) (for stations MATE0, USAL0, VEN10)
- the [caster](#) in ITA run by [SAPIENZA](#) (for stations MOSE)
- the [caster](#) in NOR run by [SK](#) (for stations Oslo, Stavanger, Trondheim, Vardo)
- the [caster](#) in POL run by [AGH](#) (for stations KRA10, KRAW0, KRAW1)
- the [caster](#) in PRT run by [IGEO](#) (for stations CASC0, FLRS0, FUNC0, GAIA0, LAGO0, PDEL0, TERC0)
- the [caster](#) in SVK run by [STUBA](#) (for stations MOP2)
- the [caster](#) in SWE run by [LM](#) (for stations kir0_euref, mar6_euref, onsa_euref, ske0_euref, spt0_euref, vis0_euref)

This server supports the [NTRIP 2.0](#) protocol. See <http://igs.bkg.bund.de/ntrip/about> for more information on NTRIP.

Uptime is 74 days, 14 hours, 17 minutes and 13 seconds, since 21/Feb/2013:23:17:15.

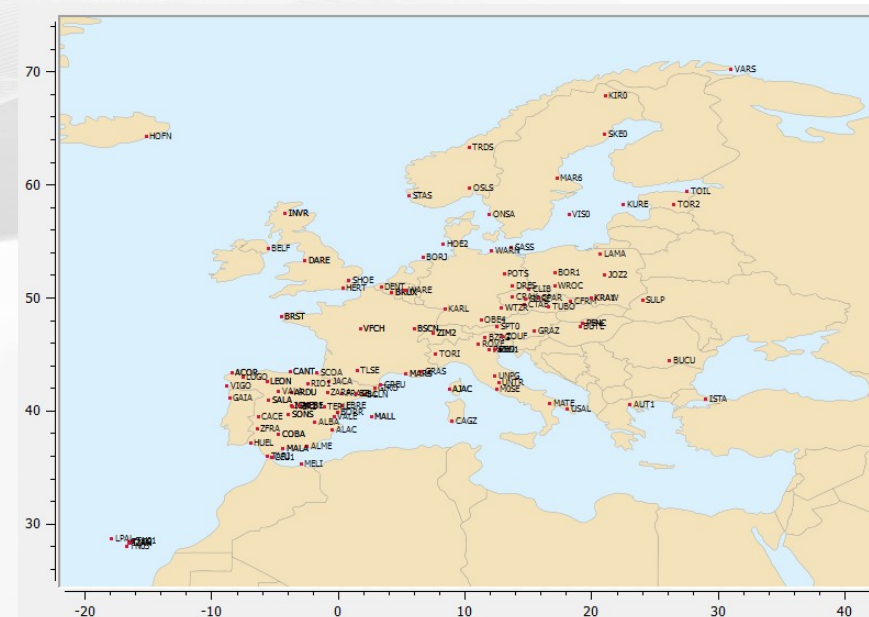
169 streams available (see [sourceable](#)), 178 listeners connected.

To apply for an account, use [this](#) form.

Below you find a selection of some of our 66 users and their application for our NTRIP streams:

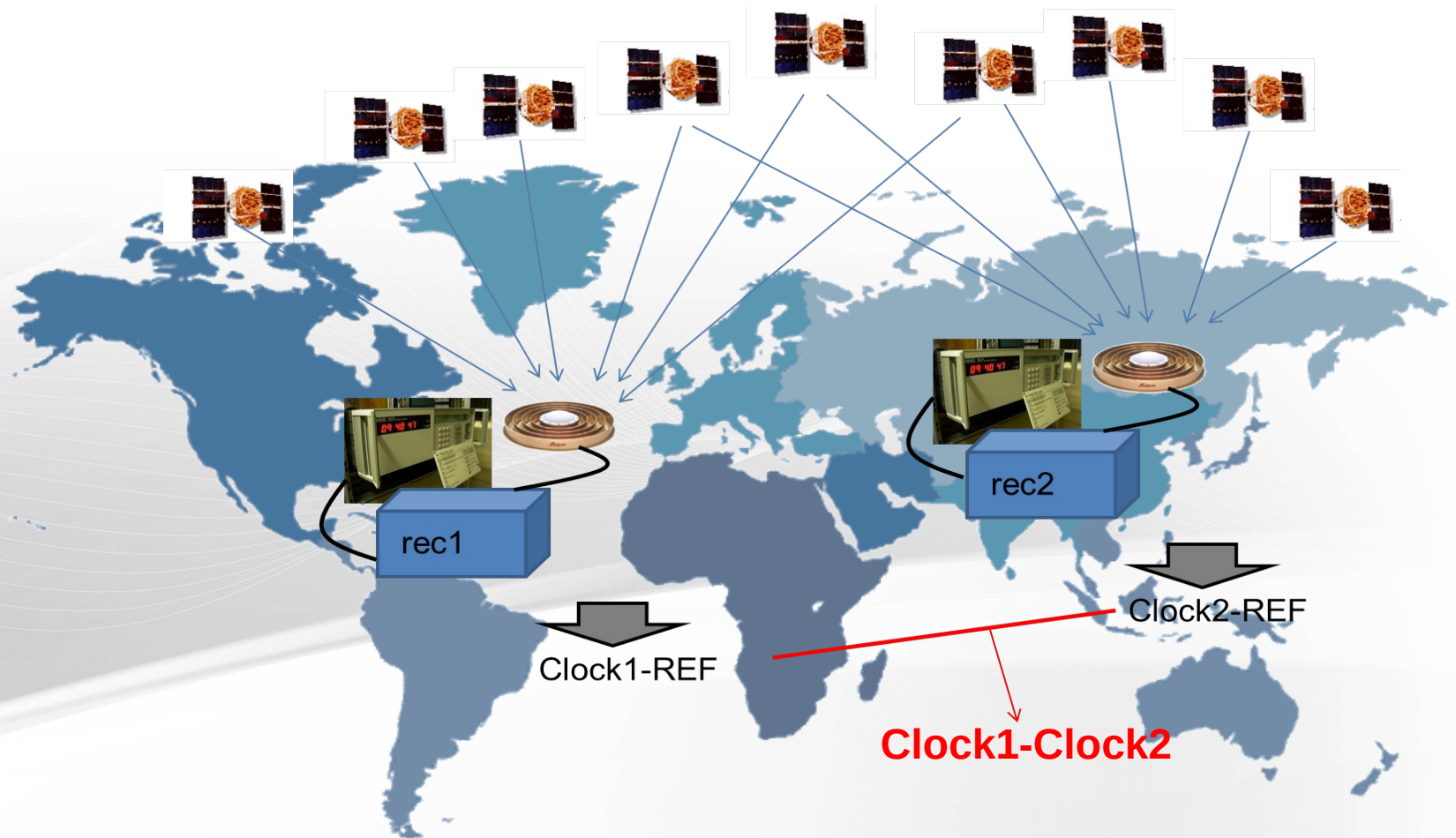
- Olha (from AUT): testing
- Bram (from BEL): low cost RTK
- Bart (from BEL): Test and generation of 1sec files

- 65 registered users (160 active listeners on average)
- 181 configured stations (135 unique streams, some redundant from 2 casters)
- Plan: secure connection (https) will become available in 2013



PPP for Time Transfer

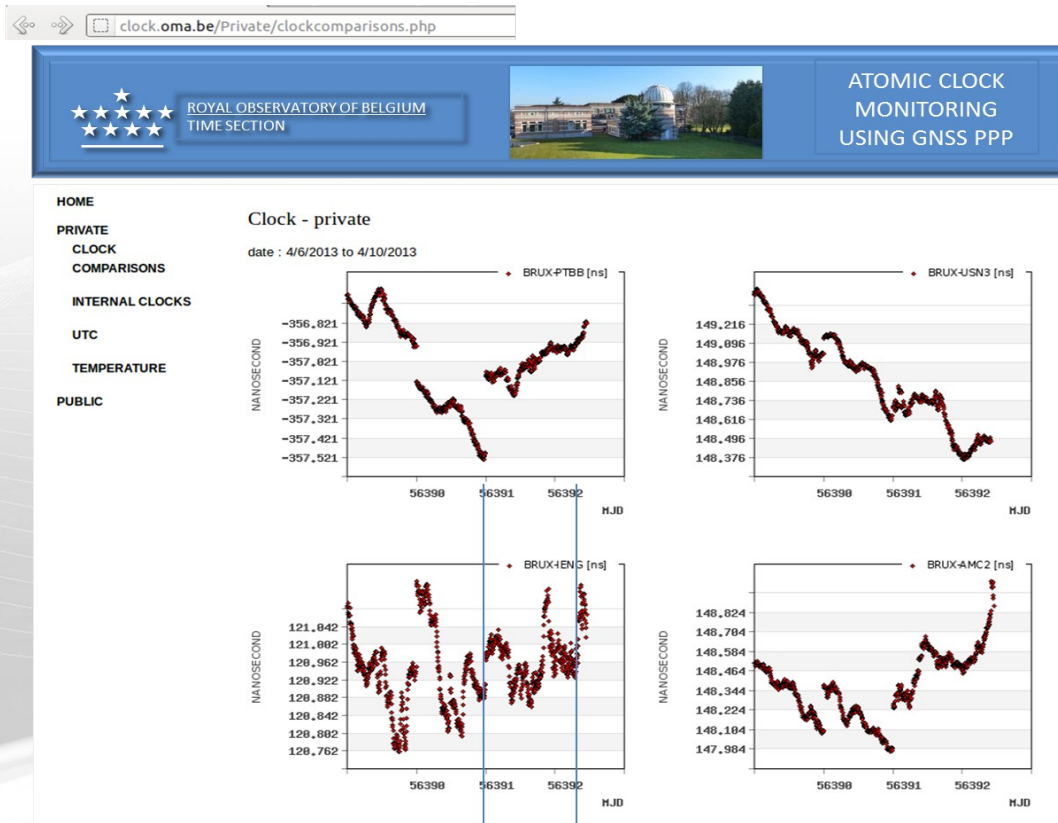
Objective : near real-time clock monitoring



Compare two remote clocks to a same reference:
REF

DATA ANALYSIS

Using IGS real-time satellite clocks and orbits +
NRCAN ultra-rapid (EMU) satellite clocks and orbits



Detection of clock problems

Phase jump :

> 1.5 ns after some minutes

frequency jump :

> $2E-13$ after 2h

> $2E-14$ after 24h

IGS

2 weeks

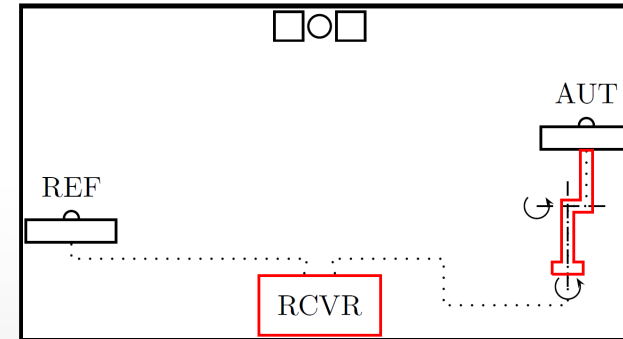
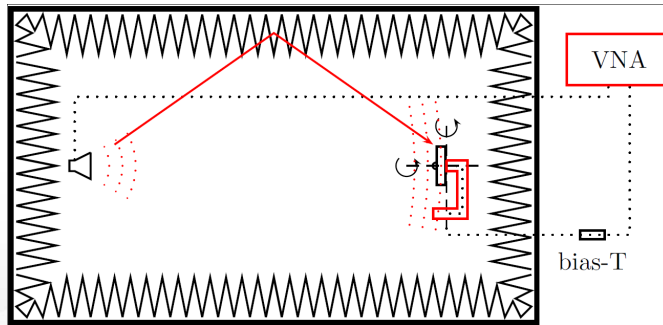
IGR

EMU

IGS real time

Antenna Calibrations

Error Sources in Absolute Individual Antenna Calibrations

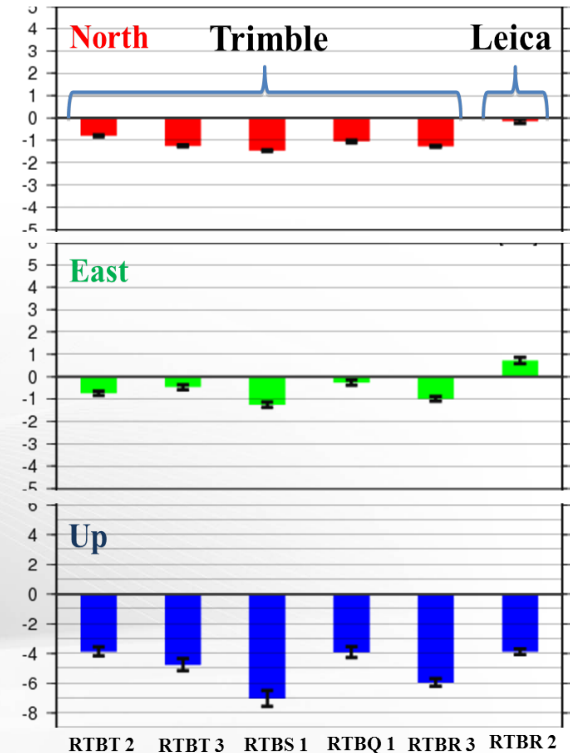


- The repeatability of a given calibration method (1 to 1.5mm) is better than differences between the chamber and robot calibrations (up to 4 mm)
- Robot calibrations using different antenna mounts (used typically in stations) can differ up to 5 mm
- The dominant error for chamber and robot calibration is **near field multipath**
- Conclusion: (sub-)millimeter absolute positioning with GNSS will only be possible after solving this near field multipath issue (that are in the calibration and in the station setup).

Antenna Calibrations

Influence of GPS receiver antenna calibration model on geodetic positioning

- Six antennas, five TRM59800.00 and one LEIAR25.R3, all individually calibrated at both Geo++ and UniBonn have been installed at ROB
- Position offsets resulting from using the two different sets of individual calibrations have been computed
- Differences in absolute positioning impacted by using either robot or chamber calibration method:
 - Up to 1.5 mm in the horizontal components
 - Up to 8 mm in the vertical component
- Plan: Field experiment at NGS (Virginia, USA), to compare baseline GPS with individually calibrated antenna and local tie (ground thruth)



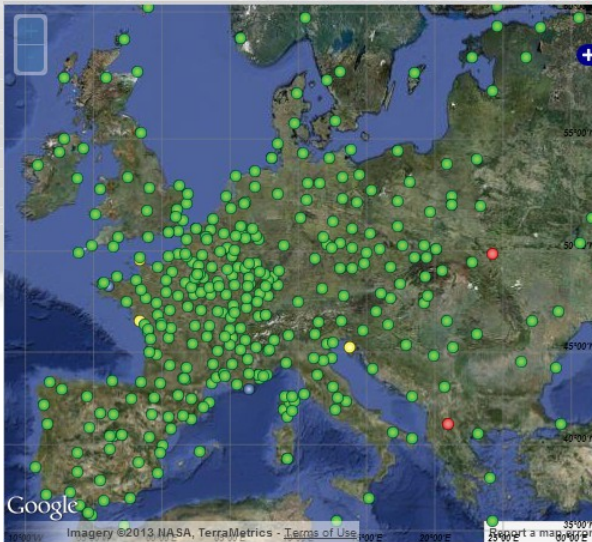
Modelling and Monitoring of the Ionosphere

▪ Thursday, May 16, 2013 - [09:45 - 10:00]

Space Weather products and studies based on EPN GNSS data at ROB
N. Bergeot, J.M. Chevalier, C. Bruyninx, E. Pottiaux, Q. Baire, J. Legrand, P.
Defraigne, W. Aerts

Modelling and Monitoring of the Troposphere

- Related Projects:
 - E-GVAP III
 - COST Action ES1206
 - Nationally founded projects
- Data used (~390/850 stations):
 - EPN (&IGS) data centers and Broadcasters
 - National densification networks
 - Real-time, Hourly and Daily RINEX
- Current analysis: Bernese v5.0, GPS-only, ZTD-only, Hourly+Daily



Modelling and Monitoring of the Troposphere

■ Domain of applications targeted:

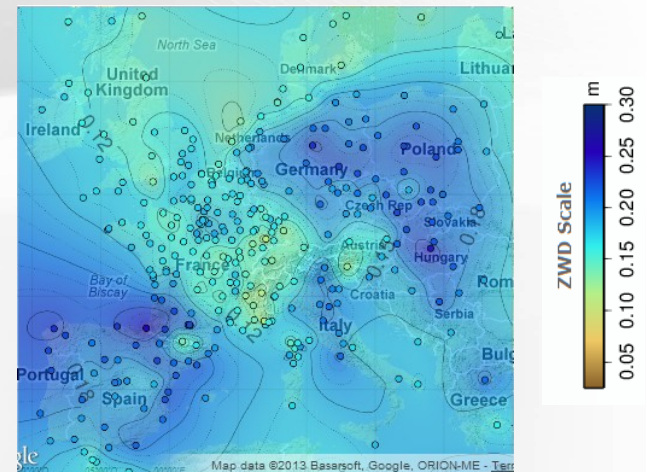
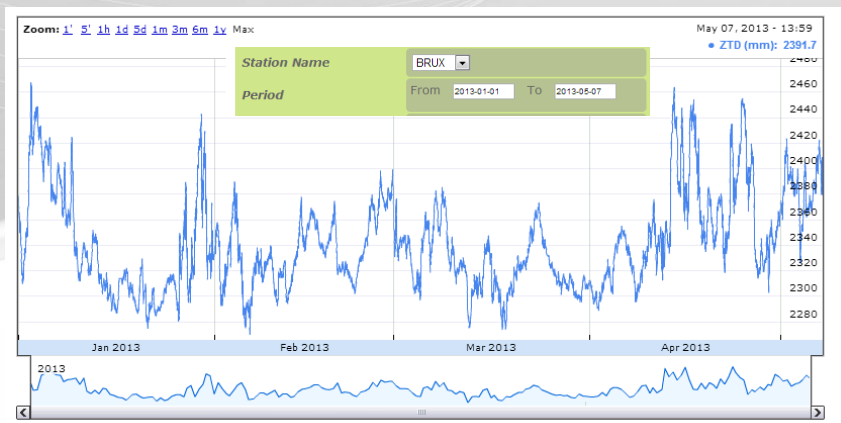
- Nowcasting of severe weather
- Regional and global NWP
- Regional climate modelling

■ Products:

- ZTD time series
- Regional Tropospheric delay maps/models

■ Plans:

- Switch to Bernese GNSS software v5.2
- GPS+GLO Analysis
- Sub-hourly data processing (15 min)
- Global analysis
- Reprocessing
- PPP
- Gradient/Slant delay estimations





Thank You For Your Attention